Proportional pressure reducing valve, pilot operated

Types ZDRE; ZDREE

Size 10
Component series 2X
Maximum pressure setting 315 bar
Maximum flow 80 l/min

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6 and 7
8 and 9
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Features
– Pilot operated valve for reducing a system pressure
– Actuation by proportional solenoid, which can be rotated
– Sandwich plate design
– Porting pattern to DIN 24340-A and ISO 4401
– 4 pressure ratings
– Valve and control electronics from a single source
– External control electronics for type ZDRE
– Linear command value/pressure characteristic curve
– Integrated electronics (OBE) with type ZDREE, with low manufacturing tolerance of the command value/pressure characteristic curve

Information on available spare parts:
www.boschrexroth.com/spc
Ordering code

<table>
<thead>
<tr>
<th>Z</th>
<th>DRE</th>
<th>10</th>
<th>VP</th>
<th>2</th>
<th>–2X/</th>
<th>M</th>
<th>G24</th>
</tr>
</thead>
</table>

Sandwich plate = Z
Proportional pressure reducing valve = DRE
For external electronics = No code
With integrated electronics = E
Size 10 = 10
Pressure reduction in channel P1 = VP
Preferred position of mating connector = 2

1) Valve contact face
(O-ring recesses in the housing)
Component series 20 to 29 = 2X
(20 to 29: unchanged installation and connection dimensions)

Pressure rating
Up to 50 bar = 50
Up to 100 bar = 100
Up to 200 bar = 200
Up to 315 bar = 315

Further details in clear text

Seal material
M = NBR seals,
V = FKM seals

Electronics interface
A1 = Command value 0 to 10 V
F1 = Command value 4 to 20 mA
No code = For ZDRE

Electrical connection
K4 = Without mating connector, with component plug to DIN EN 175301-803
for ZDRE
K31 = Without mating connector, with component plug to DIN EN 175201-804

Supply voltage of control electronics
G24 = DC voltage 24 V
M = Without check valve

Pilot oil supply/drain
Y = Pilot oil supply for directional valve from port P2,
external pilot oil drain for directional valve and ZDRE

XY = External pilot oil supply for directional valve,
external pilot oil drain for directional valve and ZDRE

L = Pilot oil supply for directional valve from P2,
internal pilot oil drain for directional valve
and external for ZDRE

XL = Pilot oil supply from P2 to X is plugged (direct operated directional valve needs no pilot oil),
pilot oil drain of directional valve is plugged (direct operated directional valve needs no pilot oil drain),
external pilot oil drain for ZDRE

Note: If no pilot oil supply is provided on the subplate, use sandwich plate HSZ 10 B097-3X/M01 for the supply.

Accessories (not included in scope of supply)
- Sandwich plate with X and Y port
  (for details, see page 3)
  Type HSZ 10 B097-3X/M01
  Material no.: R900320765
- Subplates to data sheet RE 45054
  • G 535/01 (G3/4), Material no. R900476061
  • G 536/01 (G1), Material no. R900476059
- External control for type ZDRE:
  • Analog amplifier VT-MSPA1-11-1X/V0
    of modular design to data sheet RE 30223
  • Digital amplifier VT-VSPD-1-2X/V0/.-0-1
    of Euro-card format to data sheet RE 30523
  • Analog amplifier VT-VSPA1-11-1X/V0/0
    of Euro-card format to data sheet RE 30100
- Mating connectors (for details, see page 8)
  • For ZDRE: to DIN EN 175301-803,
    Material no. R901017011
  • For ZDREE: to DIN EN 175201-804,
    Material no. R900021267 or R900223890
Symbols (① = component side, ② = plate side)

**Type ZDRE**

- Type ZDRE10VP...XY
- Type ZDRE10VP...XL
- Type ZDRE10VP...Y
- Type ZDRE10VP...L

**Type ZDREE**

- Type ZDREE10VP...XY
- Type ZDREE10VP...XL
- Type ZDREE10VP...Y
- Type ZDREE10VP...L

**Type sandwich plate HSZ**

- Dimensions (length x width x height): 100 x 70 x 30 mm
- Weight: 2.5 kg
- Size of ports X and Y: G1/4
- Dimensional sheet no.: R900262648

Sandwich plate HSZ 10 B097-3X/M01
**Function, section**

**Type ZDRE**

Valves of type ZDRE... are pilot operated pressure reducing valves of sandwich plate design in 3-way variant, i.e. with pressure limitation of the actuator pressure.

They are used for reducing a system pressure.

They basically consist of pilot part (1) with proportional solenoid (2), main valve (3) and control spool (4). The pressure in channel P1 is adjusted in dependence on the command value via proportional solenoid (2).

In the rest position, i.e. when no pressure is present in channel P2, control spool (4) opens the connection from channel P2 to P1.

The pressure in channel P1 acts via bore (5) onto spool area (6). The pilot oil for the pilot valve is taken from channel P1 and flows via bore (5), orifice (7), to spring chamber (8). From there, it is fed via valve seat (9), bore (10) and Y-line back to the tank.

The pressure required in channel P1 is pre-selected on the associated amplifier. The proportional solenoid moves valve poppet (11) towards valve seat (9) and increases the pressure in spring chamber (8). Thus, the pressure in both chambers (6) and (8) is balanced, and compression spring (12) pushes spool (4) to the right in the opening direction P2 to P1. As soon as actuator pressure P1 has increased to the value set on the pilot valve, valve poppet (11) opens and limits the pressure in spring chamber (8). Control spool (4) now moves to the left to the control position. When actuator pressure P1 exceeds the value set on the pilot valve, the control spool is pushed further to the left. It closes the connection from P2 to P1 and opens the connection P1 to tank TA1 at control land (13) until this pressure falls again to the set value.

**Type ZDREE** – with integrated electronics (OBE)

In terms of function and structure, these valves correspond to type ZDRE, except for the integrated electronics (OBE). The electronics (OBE) accommodated in housing (14) receives its supply and command value voltage via the mating connector.

The command value/pressure characteristic curve is fine-tuned with low manufacturing tolerance in the factory.

For further details on the integrated electronics (OBE), see page 9.
Pilot oil supply for directional valve mounted above

**Notes**
- On the **direct operated** directional valve, the seals for ports X and Y are missing on the connection faces of the housing. To prevent hydraulic fluid from flowing out, the pilot oil supply from P2 to X and the pilot oil drain between the directional valve and the ZDRE(E) must be plugged (variant XL).

- Leakage through the spool clearance from P to B can result in pressure building up in channel B!
- A **pilot operated** proportional directional valve in conjunction with the ZDRE(E) must have an **external pilot oil supply**.

On variants XY and XL the connection between P2 and X is plugged.

On variants Y and L port X must be plugged on the subplate.
## Technical data

(for applications outside these parameters, please consult us!)

### General

<table>
<thead>
<tr>
<th></th>
<th>ZDRE</th>
<th>ZDREE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Weight</td>
<td>kg</td>
<td>kg</td>
</tr>
<tr>
<td><strong>ZDRE</strong></td>
<td>5.1</td>
<td></td>
</tr>
<tr>
<td><strong>ZDREE</strong></td>
<td>5.2</td>
<td></td>
</tr>
</tbody>
</table>

Installation orientation

Preferred orientation of the proportional solenoid: pointing downwards or horizontal

<table>
<thead>
<tr>
<th>Storage temperature range</th>
<th>°C</th>
<th>–20 to +80</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ambiant</td>
<td>°C</td>
<td>–20 to +70</td>
</tr>
<tr>
<td><strong>ZDRE</strong></td>
<td>°C</td>
<td>–20 to +50</td>
</tr>
<tr>
<td><strong>ZDREE</strong></td>
<td>°C</td>
<td>–20 to +50</td>
</tr>
</tbody>
</table>

### Hydraulic (measured with HLP 46; \( \theta_{\text{oil}} = 40 \, ^\circ \text{C} \pm 5 \, ^\circ \text{C} \) )

<table>
<thead>
<tr>
<th>Maximum operating pressure</th>
<th>Port P1 bar</th>
<th>315</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ports P2; A; B; X</td>
<td>bar</td>
<td>350</td>
</tr>
<tr>
<td>Port T</td>
<td>bar</td>
<td>250</td>
</tr>
<tr>
<td>Port Y or L</td>
<td>Line separately and at zero pressure to tank</td>
<td></td>
</tr>
</tbody>
</table>

The pressure in an P2 must be about 20 bar higher than the required set pressure, which is to be achieved in P1.

<table>
<thead>
<tr>
<th>Maximum set pressure in port P1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pressure rating 50 bar bar 50</td>
</tr>
<tr>
<td>Pressure rating 100 bar bar 100</td>
</tr>
<tr>
<td>Pressure rating 200 bar bar 200</td>
</tr>
<tr>
<td>Pressure rating 315 bar bar 315</td>
</tr>
</tbody>
</table>

Min. set pressure in channel P1 with zero command value bar

<table>
<thead>
<tr>
<th>Permissible max. flow l/min</th>
<th>80</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pilot flow l/min</td>
<td>0.6 to 0.9</td>
</tr>
</tbody>
</table>

Hydraulic fluid

Mineral oil (HL, HLP) to DIN 51524, further hydraulic fluids on request

Hydraulic fluid temperature range °C

| –20 to +80       |

Viscosity range mm²/s

| 15 to 380 |

Permissible max. degree of contamination of the hydraulic fluid - cleanliness class to ISO 4406 (c)

| Class 20/18/15  |

Hysteresis %

| ±3 of maximum set pressure |

Repeatability %

| < ±2 of maximum set pressure |

Linearity %

| ±3.5 of maximum set pressure |

Manufacturing tolerance of command value/pressure characteristic curve, referred to hysteresis characteristic curve

<table>
<thead>
<tr>
<th>ZDRE</th>
<th>%</th>
<th>±5 of set max. pressure</th>
</tr>
</thead>
<tbody>
<tr>
<td>ZDREE</td>
<td>%</td>
<td>±1.5 of set max. pressure</td>
</tr>
</tbody>
</table>

Step response \( T_u + T_g \)

| 10 → 90% | ms | ~160 |
| 90 → 10%  | ms | ~160 |

Measured with 5 liters of a standing hydraulic fluid column in port P1

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1) The cleanliness classes specified for components must be adhered to in hydraulic systems. Effective filtration prevents malfunction and, at the same time, prolongs the service life of components.

For the selection of filters, see data sheets RE 50070, RE 50076, RE 50081, RE 50086 and RE 50088.

2) For details, see page 10

3) Adjustment in the factory
**Technical data** (for applications outside these parameters, please consult us!)

### Electrical

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Minimum solenoid current mA</td>
<td>100</td>
</tr>
<tr>
<td>Maximum solenoid current mA</td>
<td>1600 ± 10 %</td>
</tr>
<tr>
<td>Solenoid coil resistance Ω</td>
<td></td>
</tr>
<tr>
<td>Cold value at 20 °C Ω</td>
<td>5.5</td>
</tr>
<tr>
<td>Max. warm value Ω</td>
<td>8.05</td>
</tr>
<tr>
<td>Duty cycle %</td>
<td>100</td>
</tr>
</tbody>
</table>

### Electrical, integrated electronics (OBE)

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage Nominal voltage VDC</td>
<td>24</td>
</tr>
<tr>
<td>Lower limit value VDC</td>
<td>21</td>
</tr>
<tr>
<td>Upper limit value VDC</td>
<td>35</td>
</tr>
<tr>
<td>Current consumption A</td>
<td>≤ 1.5</td>
</tr>
<tr>
<td>Required fuses A</td>
<td>2, slow-blowing</td>
</tr>
<tr>
<td>Inputs Voltage V</td>
<td>0 to 10</td>
</tr>
<tr>
<td>Inputs Current mA</td>
<td>4 to 20</td>
</tr>
<tr>
<td>Output Actual current value mV</td>
<td>1 mV Δ 1 mA</td>
</tr>
<tr>
<td>Type of protection of the valve to EN 60529</td>
<td>IP 65 with mating connector mounted and locked</td>
</tr>
</tbody>
</table>
Electrical connection (dimensions in mm)

**ZDRE**

Connection to component plug

![Connection diagram](image)

Connection to mating connector

![Connection diagram](image)

Mating connector (black) to DIN EN 175301-803
Material no. R901017011
(separate order)

**ZDREE**

<table>
<thead>
<tr>
<th>Component plug pinout</th>
<th>Contact</th>
<th>Pinout of interface “A1”</th>
<th>Pinout of interface “F1”</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage</td>
<td>A</td>
<td>24 VDC ($u(t) = 21 \text{ V to 35 V}; \text{ i}_{\text{max}} \leq 1.5 \text{ A}$)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>B</td>
<td>0 V</td>
<td></td>
</tr>
<tr>
<td>Actual value reference potential</td>
<td>C</td>
<td>Reference contact F; 0 V</td>
<td>Reference contact F; 0 V</td>
</tr>
<tr>
<td>Differential amplifier input</td>
<td>D</td>
<td>0 to 10 V; $R_i = 100 \text{ kΩ}$</td>
<td>4 to 20 mA; $R_i = 100 \text{ Ω}$</td>
</tr>
<tr>
<td>E</td>
<td>Command value reference potential</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Measurement output (actual value)</td>
<td>F</td>
<td>0 to 1.6 V actual value (1 mV $\equiv$ 1 mA)</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Load resistance &gt; 10 kΩ</td>
<td></td>
</tr>
<tr>
<td>PE</td>
<td>Connected to solenoid and valve housing</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Mating connectors to DIN EN 175201-804, soldered contacts for cable cross-section 0.5 to 1.5 mm²

![Mating connectors](image)

Plastic variant,
Material no. R900021267,
(separate order)

Metal variant,
Material no. R900223890
(separate order)
Electrical connection

Connection cable for ZDREE

- Recommendation: 6-wire, 0.75 or 1 mm² plus protective earth conductor and shield
- Connect shield only on the supply side to PE
- Permissible max. length 100 m

The minimum supply voltage on the power supply unit depends on the length of the supply cable (see diagram).

Integrated electronics (OBE) of type ZDREE

Function

Power supply to electronics via connections A and B. The command value is applied to differential amplifier connections D and E.

The characteristic curve generator adapts the command value/solenoid current characteristic curve to the valve so that non-linearities in the hydraulics are compensated for and a linear command value/pressure characteristic curve is obtained.

The current regulator regulates the solenoid current independently of the solenoid coil resistance.

A chopper amplifier with a clock frequency of ca. 180 Hz to 400 Hz forms the power output stage of the electronics for controlling the proportional solenoid. The output signal is pulse-width-modulated (PWM).

For testing the solenoid current, a voltage, which is proportional to the solenoid current, can be measured between pin F(+) and pin C(−) on the plug-in connector. 1 mV corresponds to a solenoid current of 1 mA.

Block circuit diagram
Characteristic curves (measured with HLP46, \( \theta_\text{oil} = 40 \, ^\circ\text{C} \pm 5 \, ^\circ\text{C} \))

Reduced pressure in port P1 in dependence upon the command value (manufacturing tolerance)

1) For valve ZDRE the tolerance can be modified on the external amplifier (for type and data sheet, see page 2) using command value attenuator potentiometer “Gw”. The digital amplifier can be adjusted by means of parameter “Limit”. Here, the control current specified in the technical data must not be exceeded.

In order that several valves can be matched to the same characteristic curves, the pressure at a command value of 100 % must not be set higher than the maximum pressure setting of the pressure rating.

Pressure in port P1 in dependence upon the command value (at flow 0 l/min)

Pressure rating 50 bar

Pressure rating 100 bar

Pressure rating 200 bar

Pressure rating 315 bar
Characteristic curves (measured with HLP46, $\theta_{oil} = 40 \degree C \pm 5 \degree C$)
Characteristic curves (measured with HLP46, \( \vartheta_{\text{oil}} = 40 \, ^\circ\text{C} \pm 5 \, ^\circ\text{C} \))

Pressure in port P1 in dependence upon the flow

- **Pressure rating 50 bar**
  - Flow \( q_v \) in l/min
  - Pressure in port P1 in bar

- **Pressure rating 100 bar**
  - Flow \( q_v \) in l/min
  - Pressure in port P1 in bar

- **Pressure rating 200 bar**
  - Flow \( q_v \) in l/min
  - Pressure in port P1 in bar

- **Pressure rating 315 bar**
  - Flow \( q_v \) in l/min
  - Pressure in port P1 in bar

Min. set pressure in dependence upon the flow at zero command value

- Flow \( q_v \) in l/min
- Pressure in port P1 in bar
Unit dimensions (dimensions in mm)

1 Solenoid coil
2 Nameplate
3 Valve housing
4 Space required to remove mating connector
5 Identical seal rings for ports A2, B2, P2, TA2, TB2
6 Mating connector for type ZDRE (separate order)
7 Integrated electronics (type ZDREE) with component plug
8 Mating connector for type ZDREE, plastic or metal variant, (separate order)
9 Porting pattern to DIN 24340-A10 and ISO 4401-05-05-0-05 (X, Y as required)
10 O-ring and plastic nut A/F 32 for coil mounting

The nut can be loosened by turning it counter-clockwise (1 turn). The solenoid coil can then be rotated to the desired position and fixed by tightening the nut. Tightening torque: 4+1 Nm

Valve mounting screws
4 hexagon socket head cap screws ISO 4762-M6-10.9-IIZn-240h-L
(Friction coefficient $\mu_{total} = 0.09$ to 0.14);
tightening torque $M_t = 12.5$ Nm ± 10 %
or
4 hexagon socket head cap screws ISO 4762-M6-10.9
(Friction coefficient $\mu_{total} = 0.12$ to 0.17);
tightening torque $M_t = 15.5$ Nm ± 10 %
Screw length as required
Notes

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Notes